



Doplňování přechodů s pomocí ML (AI)

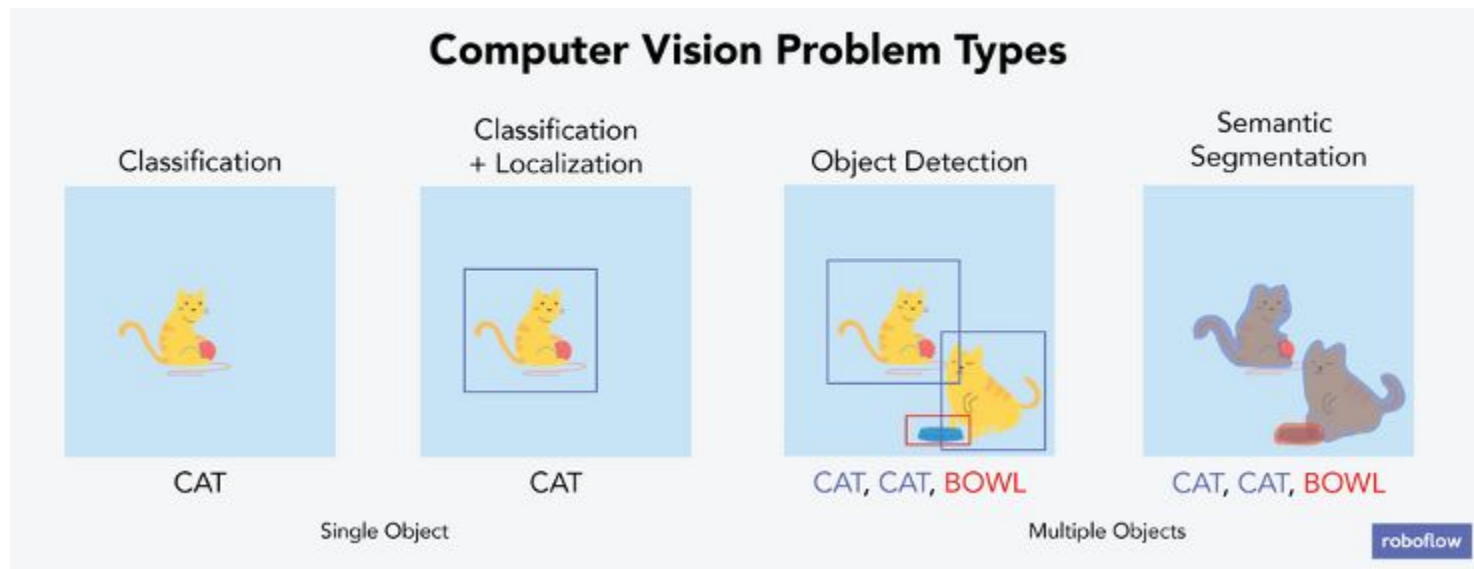
DNL852

Machine learning

- strojové učení, metoda zpracování dat
- neposkytuje exaktní výsledky, ale pravděpodobnostní
- DPZ + computer vision
- obrovský pomocník při zpracování hromady dat



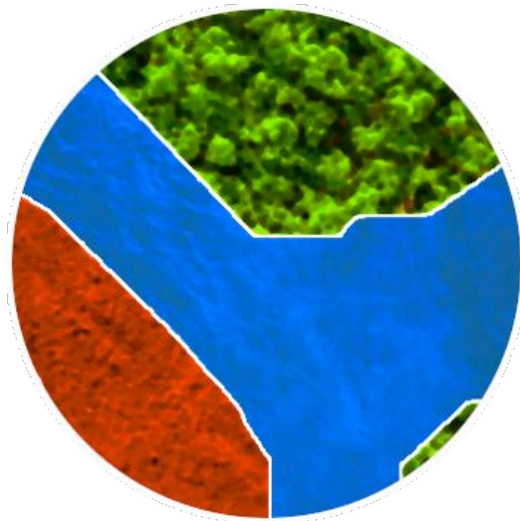
Co umí?





ML v QGISu

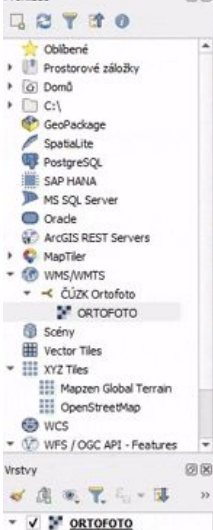
- plugin Deepness
- Poznań University of Technology
- Nvidia GPU nebo silné CPU





MapTiler Geocoding API

Prohlížeč



Deepness

Input data:

Input layer: ORTOFOTO

Processed area mask: Visible part

ONNX Model

Model type: Detector

Model file path: ids/crossings_extended_v5l6u_100e.onnx Browse...

Reload Model Load default parameters

Model info:

Legend: [BATCH_SIZE, CHANNELS, HEIGHT, WIDTH]

Inputs:

- Input 1: [1, 3, 640, 640]

Outputs:

- Output 0: [1, 5, 8500]

Input channels mapping

Processing parameters

NOTE: These options may be a fixed value for some models

Resolution [cm/px]: 12,50

Tile size [px]: 640

Batch size: 1

☐ Process using local cache

Tiles overlap:

☒ [%] 15 ☐ [px] 0

Detection parameters

NOTE: Applicable only if a detection model is used

Detector type: YOLO_Ultralytics

Inverted output shape: ☒ True

Skipped objectness: ☒ True

Ignore objectness: ☐ False

Confidence: 0,30

IoU threshold: 0,50

Training data export

Run

Tvorba vlastního modelu



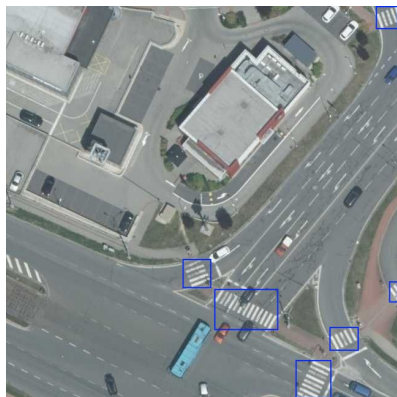
No-code cesta

- + Jednoduché
- + Plno návodů
- + Uživatelsky přívětivé nástroje
- + Cena x výkon
- Občas nutné připlatit za prémium
- Menší kontrola trénování
- Vše není open-source

Code cesta

- + Vyšší kontrola procesu učení
- + Open-source
- + Učím se cenné věci
- Časově náročné
- Krev, pot, slzy a káva
- Bez cloud computingu
vysoká cena HW
- AI vám spíš nepomůže

Tvorba vlastního modelu



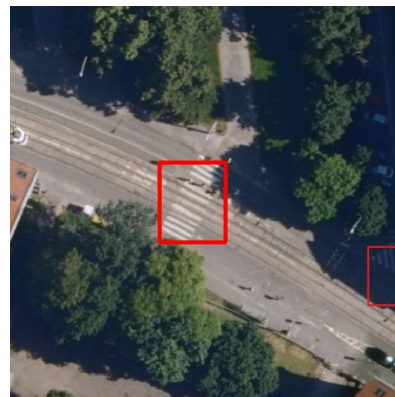
Tvorba
trénovacích
dat

90 % času



Učení
modelu

5 % času



Běh modelu

5 % času

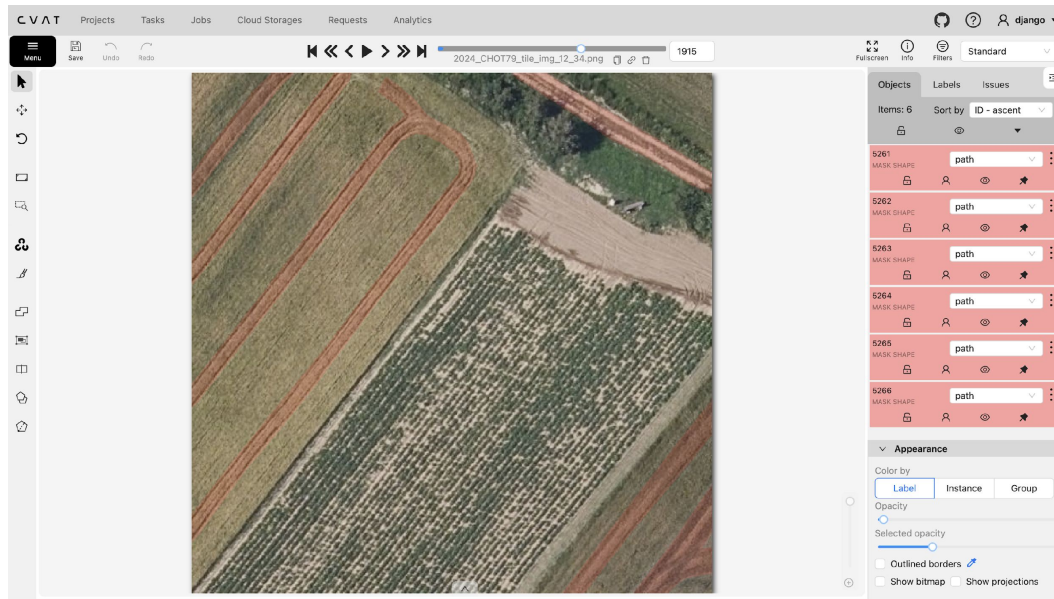


Technology stack

- **CVAT** (anotace dat)
- **Ultralytics** → **Pytorch** a YOLOv modely (trénování modelu)
- **Python + QGIS + Deepness plugin** (automatizace detekcí)

Tvorba trénovacích dat

- Ruční práce x existující datasety
- Nejdražší část ML
- Neexistuje ideální množství
- Rozmanitost
- Garbage in, garbage out



Crossing_extended

Train Model



danieloter@gmail.com

Uploaded 9 months ago

Task

Detect

Classes

1

Images

8194

Size

4.8 GB

Images

Overview

Train

Validation

Test



Search class

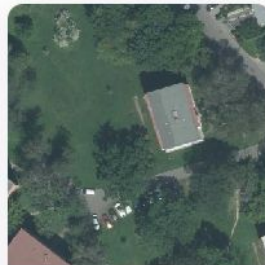


crossing

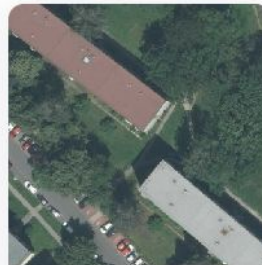
2511



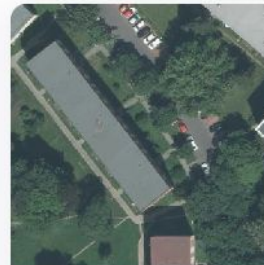
2022_BILO00_tile_img_0_1.png



2022_BILO00_tile_img_0_10.png



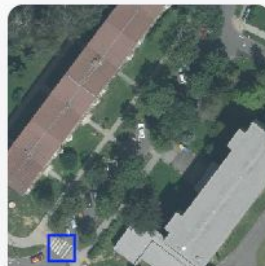
2022_BILO00_tile_img_0_11.png



2022_BILO00_tile_img_0_12.png



2022_BILO00_tile_img_0_13.png

crossing
2022_BILO00_tile_img_0_14.pngcrossing
2022_BILO00_tile_img_0_15.pngcrossing
2022_BILO00_tile_img_0_16.png

Train a Model

Follow these 3 simple steps

Dataset
Crossing_extended

Model

2

Train

3

Step 2 of 3

Model

Project

Crossings

Official

Custom

Start training from an official Ultralytics-pretrained model.

Detect Architectures

YOLO11

YOLO11n

YOLO11

YOLOv8

YOLOv8n

YOLOv8

YOLOv5u

YOLOv5nu

YOLOv5

YOLOv5u6

YOLOv5n6u

YOLOv5

Accuracy - 52.2 %

Advanced Model Configuration

Model name

Accuracy - 52.2 %

Speed - 408.4 ms

Advanced Model Configuration

Pre-trained



Epochs

100

Image size

640

Patience

100

Cache Strategy

None

RAM

Disk

Device

Auto

GPU

MPS

CPU

Batch Size

Auto

Custom

Custom

Command

Setup

Pip install `ultralytics` and `dependencies` and check software and hardware.

`pypi` `v8.3.197` `downloads` `117M` `python` `3.8` `3.9` `3.10` `3.11` `3.12`

[1]
✓ 15 s

```
%pip install ultralytics
from ultralytics import YOLO, checks, hub

checks() # Verify system setup for Ultralytics training
```

Ultralytics 8.3.197 Python-3.12.11 torch-2.8.0+cu126 CUDA:0 (Tesla T4, 15095MiB)
Setup complete (2 CPUs, 12.7 GB RAM, 39.1/112.6 GB disk)

Start

⚡ Login with your API key, load your YOLO model, and start training in 3 lines of code!

[2]

```
hub.login('f0051abc521ec4dc7dd6a1c5a772b80c99190c711e')

model = YOLO('https://hub.ultralytics.com/models/DDBrJPYQ0ZydvtxmFjxJ')
results = model.train()

*** requirements: Ultralytics requirement ['hub-sdk>=0.12'] not found, attempting AutoUpdate...

requirements: AutoUpdate success 0.7s
WARNING requirements: Restart runtime or rerun command for updates to take effect

Ultralytics HUB: New authentication successful
Ultralytics HUB: View model at https://hub.ultralytics.com/models/DDBrJPYQ0ZydvtxmFjxJ
Downloading https://github.com/ultralytics/assets/releases/download/v8.3.0/yolov5lu.pt to 'yolov5lu.pt': 100% 102.0MB 11.0MB/s 9.3s
Ultralytics 8.3.197 Python-3.12.11 torch-2.8.0+cu126 CUDA:0 (Tesla T4, 15095MiB)
engine/trainer: agnostic_nms=False, amp=True, augment=False, auto_augment=randaugument, batch=-1, bgr=0.0, box=7.5, cache=None, cfg=None, classes=None, close_mosaic
Downloading https://storage.googleapis.com/ultralytics-hub.appspot.com/users/4scTiSBxuIaM49mp0uGwg8Pi0Ye2/datasets/2RwCNuKLFPpdgA0I4J01/crossings_extended.zip to
```

Zdroje

Nemáte předplatné. Další informace
Aktuálně žádné výpočetní jednotky nejsou k dispozici. Zdroje nabízené bez dalších poplatků nejsou zaručeny. Další jednotky si můžete zakoupit zde.
Při aktuální úrovni využití může tohle spuštění vydržet až 4 hodin 30 minut.

Spravovat relace

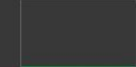
Chcete více paměti a místa na disku?
[Upgradovat na Colab Pro](#)

Python 3 Back-end Google Compute Engine (GPU)
Zobrazují se zdroje od 22:25 do 22:26

RAM systému
1.8 / 12.7 GB



RAM GPU
0.0 / 15.0 GB

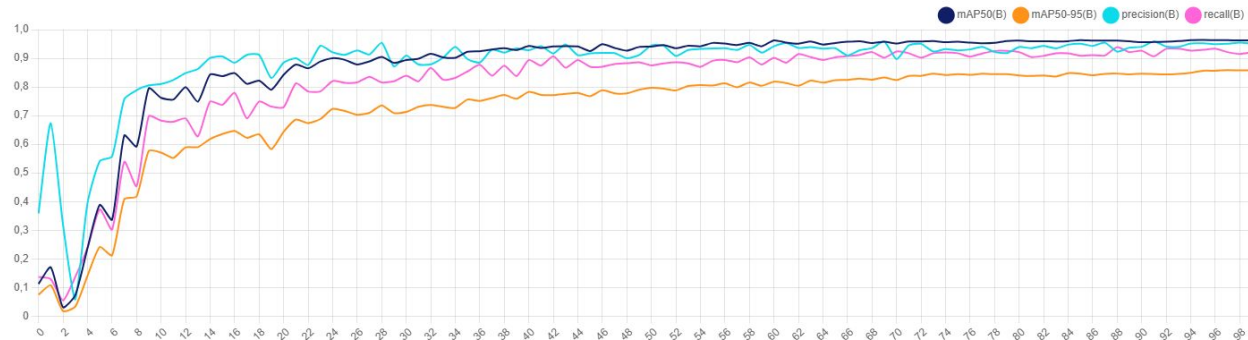


Disk

Train Configuration Charts Preview Deploy

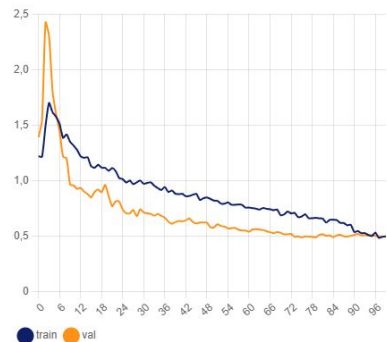
Metrics

Model accuracy measured on validation set



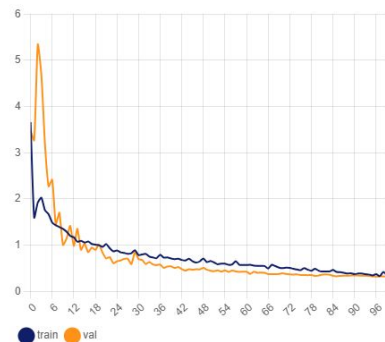
Box Loss

Difference between predicted and true boxes



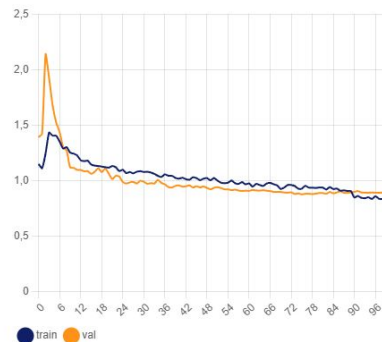
Class Loss

The accuracy of the classes in each detection



Object Loss

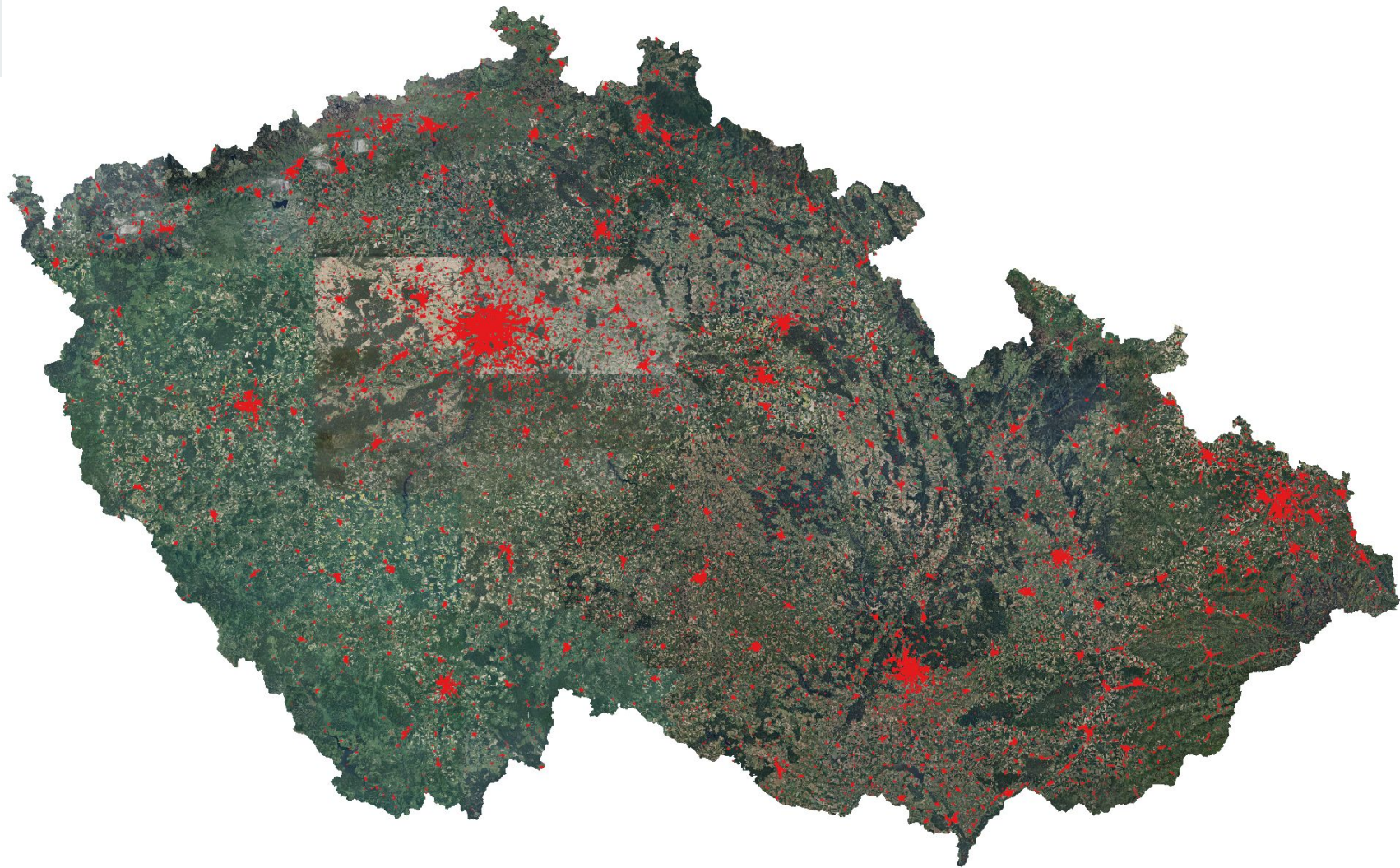
The detected objects



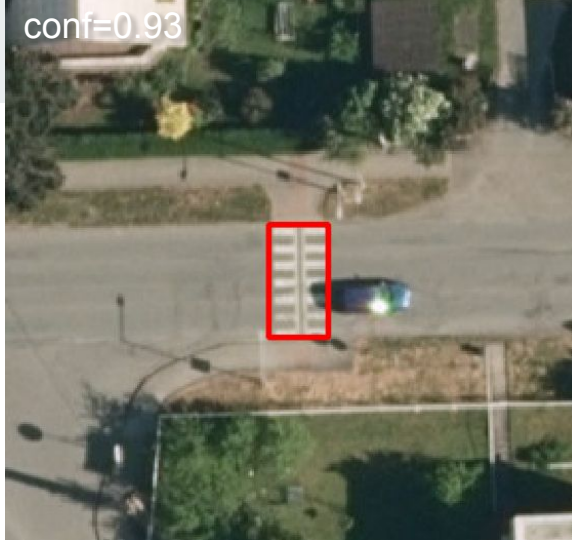
Běh modelu

- Cca 67 tisíc detekcí
- Trénováno zhruba 6 hodin v Google Colab na 2 511 anotacích
- YOLOv5
- Detekce všech přechodů
 - 16 tisíc ortofoto snímků
 - 12,5 cm/px
 - Cca 2 týdny běhu RTX 4080 Super
- 10.5281/zenodo.15746210
- běží detekce nad SK ortofotem (díky Tomas_J!)





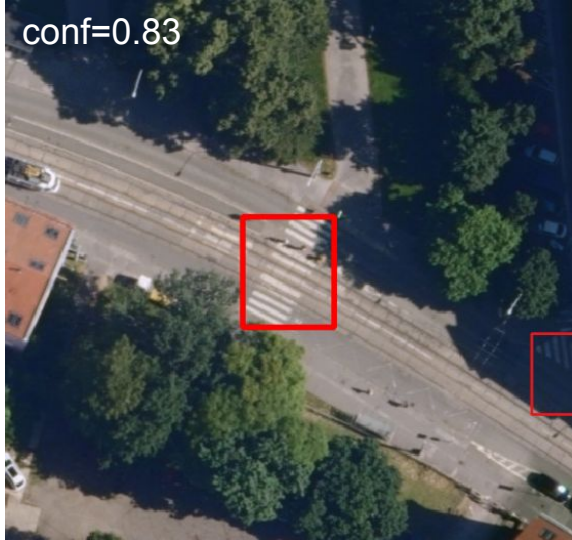
conf=0.93



conf=0.55



conf=0.83

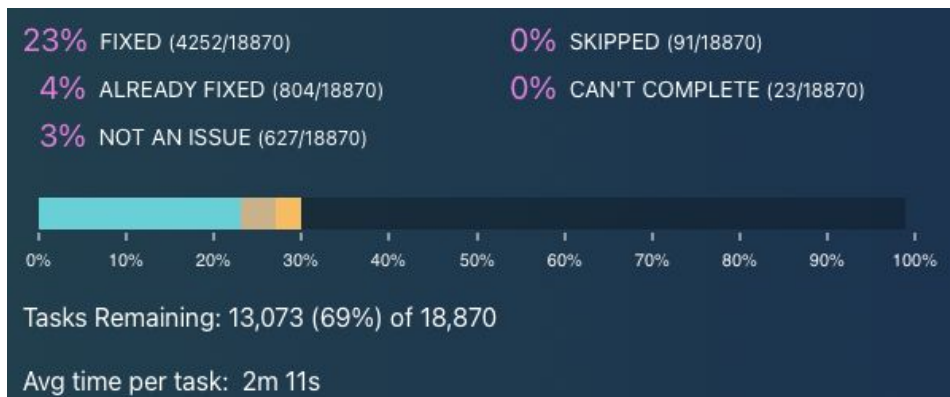
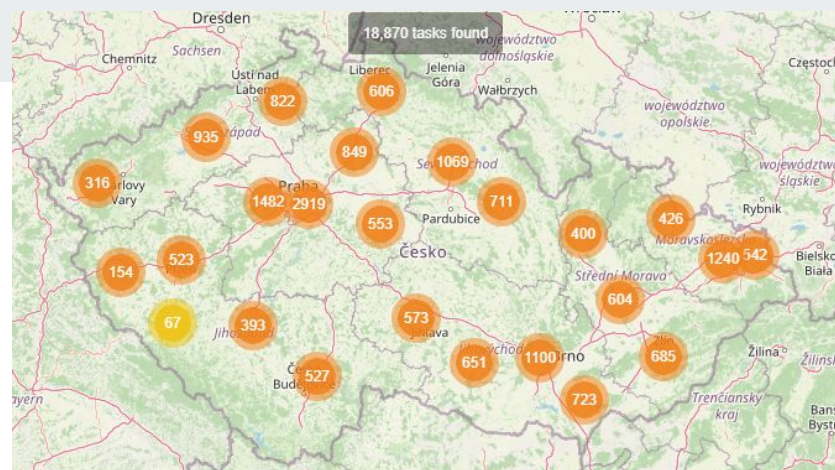


conf=0.75



Proč přechody?

- Kvalita dat OpenStreetMap
- Vyhledání chybějících přechodů
- Komunitní doplnění





Adding highway=crossing in Czechia 🔒 ...

Crossings in Czechia



INSTRUCTIONS ✓

MAP WITH THE LATEST ČÚZK ORTHOIMAGERY (ČÚZK ORTOFOTO)!

This task focuses on adding the highway=crossing tag on nodes. Please follow the instructions on the OSM Wiki to map the crossing properly (<https://wiki.openstreetmap.org/wiki/Tag:highway%3Dcrossing>). Also, add corresponding crossing and crossing:markings=* tags.

COMPLETION

Add MR Tags ⓘ

Edit in JOSM ▾

I fixed it!

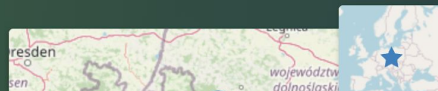
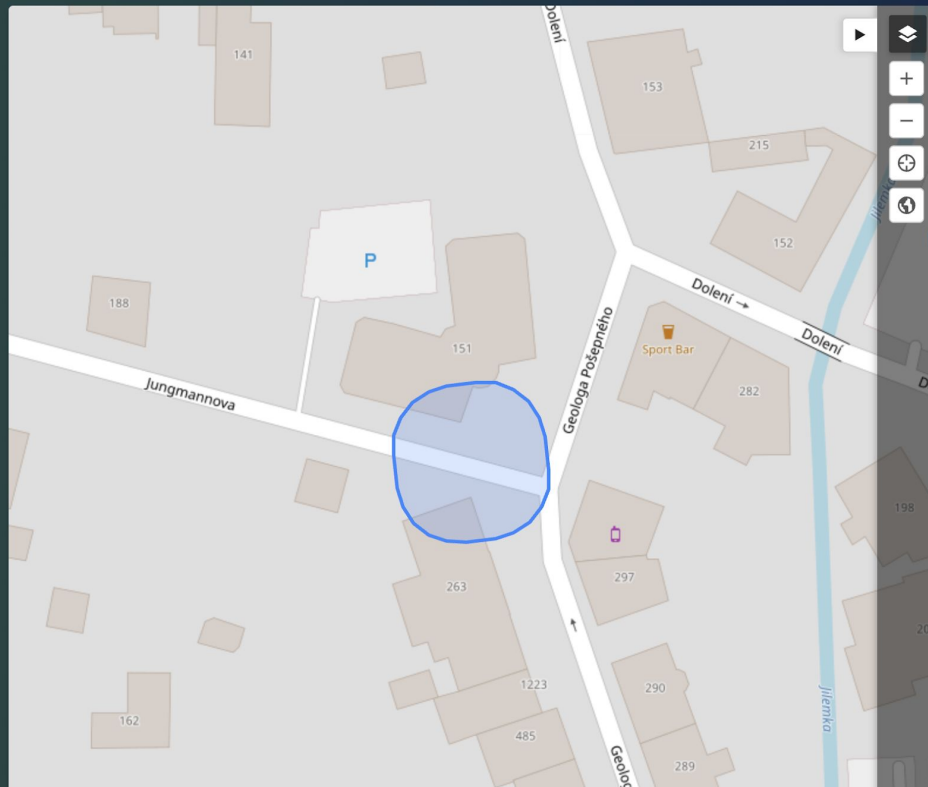
Already fixed

Not an Issue

Can't Complete

Skip

LOCATION

Switch to: Lat/LonCurrent Mode: ☒ Classic Mode

Java OpenStreetMap Editor interface showing a map view and various toolbars.

Top Toolbar: Includes icons for file operations (Open, Save, Download, Upload), navigation (Home, Previous, Next, Find), editing (Add, Delete, Copy, Paste, Undo, Redo), and map features (Pick Residential Area, Select Duplicate Buildings, Select Non Orthogonal Buildings, Select Non Orthogonal Roads).

Left Toolbar: Includes icons for map navigation (Home, Previous, Next, Find), editing (Add, Delete, Copy, Paste, Undo, Redo), and map features (Pick Residential Area, Select Duplicate Buildings, Select Non Orthogonal Buildings, Select Non Orthogonal Roads).

Map View: Displays an aerial view of a street intersection. A red line indicates a selected area. A scale bar shows 0 to 5.00 m. Labels on the map include "Geologia Postgrado" and "Jungmannova".

Right Panel (Layers and Tools):

- Layers:** Shows a list of layers. The selected layer is "MR Task 293701052". Below it is "Elevation Profile".
- Tags/Memberships:** Section for managing tags and memberships. It includes a "Select objects for which to change tags." prompt and buttons for "Add", "Edit", and "Delete".
- Selection:** Section for selecting objects. It includes a "Select" button, a "Search" dropdown, and a "History" button.
- Relations: 13:** Section for managing relations. It shows a list of relations: "associatedStreet (336571, 4 members, incomplete)" and "multipolygon ('civic', 5 members, incomplete)".
- Authors:** Section for managing authors. It includes a table with columns "Author", "# Objects", and "%".
- Validation Results:** Section for managing validation results. It includes a "Select" button, a "Lookup" button, and a "Valida..." button.
- Map Paint Styles:** Section for managing map paint styles. It includes a list of styles: "Wireframe View", "JOSM default (MapCSS)", "Apple Paint Style", "Missing Maps / Youth Mappers Validators Checks", and "Inline Validation".
- Todo list:** Section for managing the todo list.

Bottom Status Bar: Displays coordinates (50.6075403, 15.5086211) and a message "(no object)".

The screenshot displays the Java OpenStreetMap Editor interface. The main map area shows an aerial view of a residential street with a pedestrian crossing. A red line indicates the crossing's path, and a blue dot marks a specific point on it. The top toolbar contains various editing tools like pan, zoom, and line drawing. The right sidebar includes a 'Layers' panel, a 'Tags' panel, and a 'Memberships' panel. The 'Tags' panel shows a table with keys and values for the selected object.

Layers

- [3] MR Task 293701052 *
- [2] Elevation Profile

Tags: 3 / Memberships: 0

Key	Value
crossing:island	no
crossing:markings	zebra
highway	crossing

Change 1 object

Highways/Waypoints/Pedestrian Crossing

Pedestrian crossing type: **crossing**

Markings:

- ☐ no
- ☐ yes
- ☐ surface
- ☐ lines
- ☐ lines:paired
- ☐ dashes
- ☐ dots
- ☒ **zebra**

Crossing type name: **crossing_ref**

Kerb: **kerb**

Crossing attendant: **supervised**

Tactile Paving: **tactile_paving**

☐ With island

☐ Cross by bicycle

☐ Cross on horseback

In case of traffic signals:

☐ With signals

☐ Button operated

☐ Sound signals

[More information about this feature](#)

Apply Preset **Cancel** **Help**

Wireframe View

- JOSM default (MapCSS)
- ☒ Apple Paint Style
- Missing Maps / Youth Mappers Validators Checks
- Inline Validation

Todo list

50.6078019 15.5085979 91.40 ° (no object)

to toggle; Shift-Meta to rotate selected; Alt-Meta to scale selected; or change selection

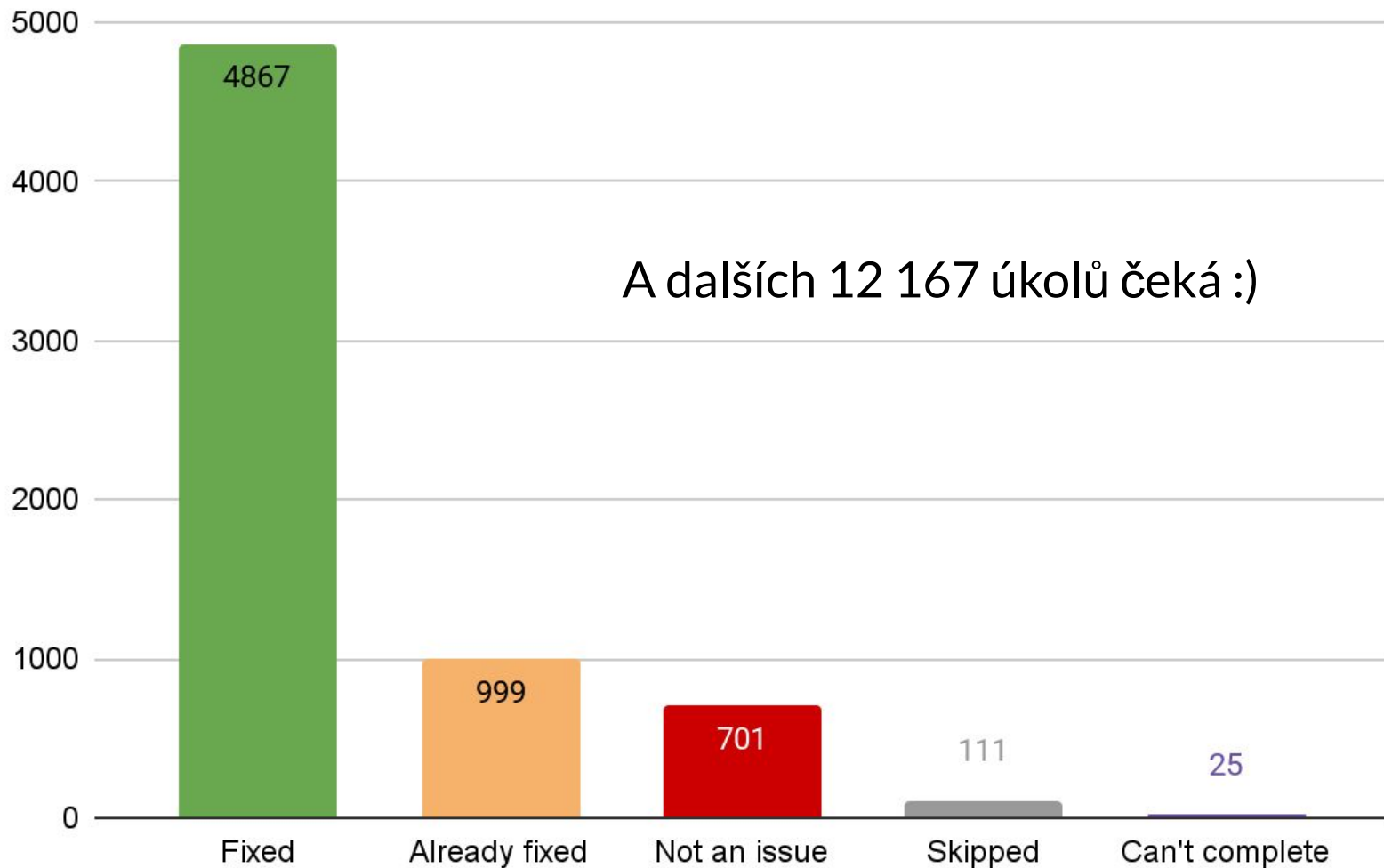


An aerial photograph showing a street intersection. A yellow line representing a road runs horizontally across the middle, labeled "Sladkovského". Another road runs vertically through the center, labeled "Havlíkova". A red rectangle highlights a specific area at the intersection. Various colored dashed lines (green, purple, orange) and solid lines (blue, white) are overlaid on the image, likely representing different types of boundaries or survey points. Small black squares and crosses mark specific locations along the roads and within the highlighted area. The background shows green trees, a sidewalk, and parts of buildings.





Počet úkolů



A dalších 12 167 úkolů čeká :)